

Technical sheet

Krypton 8 Robotics kit

What's in the box?



Programmable Logic Controller:

User friendly main control board. This is the brain for every project in this course. The controller manages the program signals from and to each sensor and actuator. It connects to a mobile device through a Wi-Fi connection. It offers a simple UI through an LCD touchscreen.

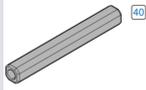
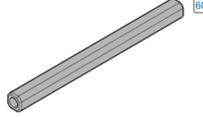
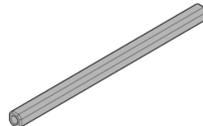
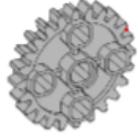


Main characteristics:

- RJ11 connector pins for 7 sensors, 4 motors, and 1 camera module
- Quad core Cortex-A7 processor @1.3GHz
- 1.6GB storage
- 64KB RAM
- Wi-Fi & Bluetooth modules
- 2.3" LCD touchscreen
- Embedded sensors: Gyroscope, Compass, Microphone.
- 1500mAh rechargeable Lithium battery

Structural parts:

A total of **1,550** plastic parts are included in this kit. These structural components are meant to be assembled without the need of special tools.

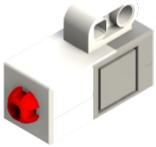
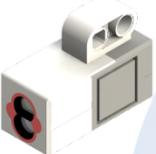
Part list				
Porous beam Black 30mm x20 	Porous beam Red 30mm x16 	Porous beam Green 30mm x16 	Porous beam Yellow 30mm x16 	Porous beam Blue 30mm x16 
Porous beam 20mm x25 	Porous beam Gray 30mm x20 	Porous beam gray 70mm x40 	Porous beam White 110mm x30 	Axle(20mm) x20 
Axle (30mm) x20 	Axle (40mm) x20 	Axle(50mm) x20 	Axle (60mm) x20 	Axle(80mm) x20 
Coupling (90°) x14 	Mecanum Wheel x 4 	Guide Wheel x6 	Coupling(20mm) x14 	Marble x4 
Bolt(20mm) x343 	Bolt(30mm) x160 	Bolt(15mm) x60 	Axle sleeve x40 	Beam U shape x4 
Middle A connector x10 	Slide bearing x14 	Short bolt(2mm) x16 	Middle L connector x20 	Middle H connector x10 
Porous beam 90° x25 	Porous beam 126.87° x25 	Porous beam 90° x25 	Porous beam 126.87° x25 	Gray gear #1 x10 

Black gear #1 x10 	Yellow gear #1 x10 	Gray gear #1 x10 	Black gear #2 x10 	Yellow gear #2 x10 
Cube x45 	Half cube x40 	Cube connector x40 	Slope cube x15 	60° cube x12 
Non-slip rubber x50 	Rail x100 	Rail rim x8 	Tire x4 	Rim x4 
Square beam x16 	1# Slab x14 	4# Slab x4 	Cables x12 	

Sensors

These components are used to collect data from the environment. Each sensor must be connected to the PLC board and be programmed individually. **Total: 33 sensors**

Sensor list			
Picture	Name	Quantity	Function
-	Compass (embedded)	1	Using the earth's magnetic field, determines the position in which the PLC is facing.
-	Gyroscope (embedded)	1	Determines the acceleration force magnitude in X, Y and Z axis.
-	Microphone (embedded)	1	Records any environmental audio when active.
-	Position (embedded in motor)	7	Determines motor's axis actual position and RPM

	Touch	8	Recalls the current state of the button, either pressed or not.
	Grayscale	9	Analyses the color of an object (how light or dark) to determine its shade of gray.
	Color	2	Determines the color of an object in front of it (red, green, blue, yellow, or white) or the intensity of a light shining upon the sensor. Best reads at 0.5in.
	Ultrasonic	3	Using an ultrasonic soundwave calculates the distance between the sensor and an object in front of it. Best reads from 1 to 25in.
	Camera	1	Takes a picture when activated, which can later be accessed on the controllers storage.

Actuators

These components are used to create motion within an assembly. Each actuator must be connected to the PLC board and be programmed individually. **Total: 10 Actuators**

Actuator list			
Picture	Name	Quantity	Function
-	RGB LED (embedded)	1	Individually controllable RGB LED light.
-	Speaker (embedded)	2	Play any sound coming from the PLC board.
	Small motor	4	Creates rotational motion at low torque and high speeds.

	Big motor	3	Creates rotational motion at high torque and low speeds.
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Minimum Hardware Requirements

Mobile Device: with Operating Systems iOS 9.3 or later or Android Oreo 8.0 or later. Memory: 8GB Minimum and RAM: 2GB Minimum.

Applications:

Download the following Apps in your device:

- Abilix Krypton Mobile App

This application encloses every functionality the Krypton robotics family has. The app contains introductory activities, a project gallery, interactive 3D assembly manuals, and three different block-based programming environments.



The app is available for iOS and Android users:

Apple AppStore: <https://apps.apple.com/mx/app/abilix-krypton-todays-future/id1140118489>

Google PlayStore: <https://play.google.com/store/apps/details?id=com.partnerx.CRobotgplay>

The App Includes 3 programming modules:

- Block-based Programming (Krypton Project Programming)

This programming tool is the easiest way to start programming robotics. The user works in an environment in which there are pre-programmed blocks; each block contains a predefined sequence which makes the robot move in a certain way. In this tool, there is no chance for failure since every block has been previously proven to work. This programming method is recommended for absolute beginners.



- Krypton Scratch Programming

This programming tool uses natural language blocks to program the robot; works just as any other Scratch programming environment. If you are already familiar using Scratch, this tool will fit you best.



- Krypton Chart Programming

This tool follows a flowchart programming scheme. Just as a regular flowchart program in any environment, the program will play from top to bottom following each block's configuration. This is the ideal tool for a more complete and complex project development.

